# CLASSIFICATION OF TWISTED ALGEBRAS OF 3-DIMENSIONAL SKLYANIN ALGEBRAS

MASAKI MATSUNO

ABSTRACT. A twisting system is one of the major tools to study graded algebras, however, it is often difficult to construct a (non-algebraic) twisting system if a graded algebra is given by generators and relations. In this paper, we show that a twisted algebra of a geometric algebra is determined by a certain automorphism of its point variety. As an application, we classify twisted algebras of 3-dimensional Sklyanin algebras up to graded algebra isomorphism.

### 1. INTRODUCTION

This paper is based on [5]. The notion of twisting system was introduced by Zhang in [8]. If there is a twisting system  $\theta = \{\theta_n\}_{n \in \mathbb{Z}}$  for a graded algebra A, then we can define a new graded algebra  $A^{\theta}$ , called a twisted algebra. Zhang gave a necessary and sufficient algebraic condition via a twisting system when two categories of graded right modules are equivalent ([8, Theorem 3.5]). Although a twisting system plays an important role to study a graded algebra, it is often difficult to construct a twisting system on a graded algebra if it is given by generators and relations.

Mori introduced the notion of geometric algebra  $\mathcal{A}(E,\sigma)$  which is determined by a geometric data which consists of a projective variety E, called the point variety, and its automorphism  $\sigma$ . For these algebras, Mori gave a necessary and sufficient geometric condition when two categories of graded right modules are equivalent ([6, Theorem 4.7]). By using this geometric condition, we can easily construct a twisting system.

Cooney and Grabowski defined a groupoid whose objects are geometric noncommutative projective spaces and whose morphisms are isomorphisms between them. By studying a correspondence between the morphisms of this groupoid and a twisting system, they showed that the morphisms of this groupoid are parametrized by a set of certain automorphisms of the point variety ([1, Theorem 28]).

In this paper, we focus on studying a twisted algebra of a geometric algebra  $\mathcal{A}(E, \sigma)$ . For a twisting system  $\theta$  on A, we set  $\Phi(\theta) := \overline{(\theta_1|_{A_1})^*} \in \operatorname{Aut}_k \mathbb{P}(A_1^*)$  by dualization and projectivization. We find a subset  $M(E, \sigma)$  of  $\operatorname{Aut}_k \mathbb{P}(A_1^*)$  parametrizing twisted algebras of A up to isomorphism. We show that a twisted algebra of a geometric algebra is determined by a certain automorphism of its point variety. As an application, we classify twisted algebras of 3-dimensional Sklyanin algebras up to graded algebra isomorphism.

The detailed version of this paper is [5].

### 2. Twisting systems and twisted algebras

Throughout this paper, we fix an algebraically closed field k of characteristic zero and assume that a graded algebra is an N-graded algebra  $A = \bigoplus_{i \in \mathbb{N}} A_i$  over k. A graded algebra  $A = \bigoplus_{i \in \mathbb{N}} A_i$  is called *connected* if  $A_0 = k$ . Let  $\operatorname{GrAut}_k A$  denote the group of graded algebra automorphisms of A. We denote by  $\operatorname{GrMod} A$  the category of graded right A-modules. We say that two graded algebras A and A' are graded Morita equivalent if two categories  $\operatorname{GrMod} A$  and  $\operatorname{GrMod} A'$  are equivalent.

**Definition 1.** Let A be a graded algebra. A set of graded k-linear automorphisms  $\theta = \{\theta_n\}_{n \in \mathbb{Z}}$  of A is called a twisting system on A if

$$\theta_n(a\theta_m(b)) = \theta_n(a)\theta_{n+m}(b)$$

for any  $l, m, n \in \mathbb{Z}$  and  $a \in A_m, b \in A_l$ . The twisted algebra of A by  $\theta$ , denoted by  $A^{\theta}$ , is a graded algebra A with a new multiplication \* defined by

$$a * b = a\theta_m(b)$$

for any  $a \in A_m$ ,  $b \in A_l$ . A twisting system  $\theta = \{\theta_n\}_{n \in \mathbb{Z}}$  is called *algebraic* if  $\theta_{m+n} = \theta_m \circ \theta_n$  for every  $m, n \in \mathbb{Z}$ .

We denote by TS(A) the set of twisting systems on A. Zhang [8] found a necessary and sufficient algebraic condition for  $GrModA \cong GrModA'$ .

**Theorem 2** ([8, Theorem 3.5]). Let A and A' be graded algebras finitely generated in degree 1 over k. Then  $\operatorname{GrMod} A \cong \operatorname{GrMod} A'$  if and only if A' is isomorphic to a twisted algebra  $A^{\theta}$  by a twisting system  $\theta \in \operatorname{TS}(A)$ .

**Definition 3.** For a graded algebra A, we define

$$TS_0(A) := \{ \theta \in TS(A) \mid \theta_0 = id_A \}$$
  

$$TS_{alg}(A) := \{ \theta \in TS_0(A) \mid \theta \text{ is algebraic } \}$$
  

$$Twist(A) := \{ A^{\theta} \mid \theta \in TS(A) \} /_{\cong}$$
  

$$Twist_{alg}(A) := \{ A^{\theta} \mid \theta \in TS_{alg}(A) \} /_{\cong}.$$

**Lemma 4** ([8, Proposition 2.4]). Let A be a graded algebra. For every  $\theta \in TS(A)$ , there exists  $\theta' \in TS_0(A)$  such that  $A^{\theta} \cong A^{\theta'}$ .

It follows from Lemma 4 that

$$\operatorname{Twist}(A) = \{A^{\theta} \mid \theta \in \operatorname{TS}_0(A)\}/\cong,\$$

so we may assume that  $\theta \in \mathrm{TS}_0(A)$  to study  $\mathrm{Twist}(A)$ . By the definition of twisting system, it follows that  $\theta \in \mathrm{TS}_{\mathrm{alg}}(A)$  if and only if  $\theta_n = \theta_1^n$  for every  $n \in \mathbb{Z}$  and  $\theta_1 \in \mathrm{GrAut}_k A$ , so

$$\operatorname{Twist}_{\operatorname{alg}}(A) = \{A^{\phi} \mid \phi \in \operatorname{GrAut}_k A\}/\cong$$

where  $A^{\phi}$  means the twisted algebra of A by  $\{\phi^n\}_{n\in\mathbb{Z}}$ .

#### 3. Twisted algebras of geometric algebras

Let V be a finite dimensional k-vector space and A = T(V)/(R) be a quadratic algebra where T(V) is a tensor algebra over k and R is a subspace of  $V \otimes V$ . Since an element of R defines a multilinear function on  $V^* \times V^*$ , we can define a zero set associated to R by

$$\mathcal{V}(R) = \{ (p,q) \in \mathbb{P}(V^*) \times \mathbb{P}(V^*) \mid g(p,q) = 0 \text{ for any } g \in R \}.$$

**Definition 5.** Let A = T(V)/(R) be a quadratic algebra. A geometric pair  $(E, \sigma)$  consists of a projective variety  $E \subset \mathbb{P}(V^*)$  and  $\sigma \in \operatorname{Aut}_k E$ . We say that A is a geometric algebra if there exists a geometric pair  $(E, \sigma)$  such that

- (G1)  $\mathcal{V}(R) = \{(p, \sigma(p)) \in \mathbb{P}(V^*) \times \mathbb{P}(V^*) \mid p \in E\},\$
- (G2)  $R = \{g \in V \otimes V \mid g(p, \sigma(p)) = 0 \text{ for all } p \in E\}.$

In this case, we call E the *point variety* of A, and write  $A = \mathcal{A}(E, \sigma)$ .

We use the following notations introduced in [1]:

**Definition 6.** Let  $E \subset \mathbb{P}(V^*)$  be a projective variety and  $\sigma \in \operatorname{Aut}_k E$ . We define

$$\begin{aligned} \operatorname{Aut}_k(E \uparrow \mathbb{P}(V^*)) &:= \{ \tau \in \operatorname{Aut}_k E \mid \tau = \overline{\tau}|_E \text{ for some } \overline{\tau} \in \operatorname{Aut}_k \mathbb{P}(V^*) \}, \\ \operatorname{Aut}_k(\mathbb{P}(V^*) \downarrow E) &:= \{ \tau \in \operatorname{Aut}_k \mathbb{P}(V^*) \mid \tau|_E \in \operatorname{Aut}_k E \}, \\ Z(E, \sigma) &:= \{ \tau \in \operatorname{Aut}_k(\mathbb{P}(V^*) \downarrow E) \mid \sigma \tau|_E \sigma^{-1} = \tau|_E \}, \\ M(E, \sigma) &:= \{ \tau \in \operatorname{Aut}_k(\mathbb{P}(V^*) \downarrow E) \mid (\tau|_E \sigma)^i \sigma^{-i} \in \operatorname{Aut}_k(E \uparrow \mathbb{P}(V^*)) \; \forall i \in \mathbb{Z} \}, \\ N(E, \sigma) &:= \{ \tau \in \operatorname{Aut}_k(\mathbb{P}(V^*) \downarrow E) \mid \sigma \tau|_E \sigma^{-1} \in \operatorname{Aut}_k(E \uparrow \mathbb{P}(V^*)) \}. \end{aligned}$$

Note that  $Z(E,\sigma) \subset M(E,\sigma) \subset N(E,\sigma) \subset \operatorname{Aut}_k(\mathbb{P}(V^*) \downarrow E)$ , and  $Z(E,\sigma)$ ,  $N(E,\sigma)$  are subgroups of  $\operatorname{Aut}_k(\mathbb{P}(V^*) \downarrow E)$ .

Let  $A = \mathcal{A}(E, \sigma)$  be a geometric algebra. The map  $\Phi : \mathrm{TS}_0(A) \to \mathrm{Aut}_k \mathbb{P}(A_1^*)$  is defined by  $\Phi(\theta) := \overline{(\theta_1|_{A_1})^*}$ . This map plays an important role to study twisted algebras of geometric algebras.

**Lemma 7** ([5, Lemma 3.3 and Lemma 3.4]). Let  $A = \mathcal{A}(E, \sigma)$  be a geometric algebra.

- (1)  $\Phi(\mathrm{TS}_0(A)) = M(E, \sigma).$
- (2)  $\Phi(\mathrm{TS}_{\mathrm{alg}}(A)) = Z(E, \sigma).$

The following is one of the main results.

**Theorem 8** ([5, Theorem 3.5]). Let  $A = \mathcal{A}(E, \sigma)$  be a geometric algebra.

- (1) Twist(A) = { $\mathcal{A}(E, \tau|_E \sigma) \mid \tau \in M(E, \sigma)$ }/ $\cong$ .
- (2) Twist<sub>alg</sub>(A) = { $\mathcal{A}(E, \tau|_E \sigma) \mid \tau \in Z(E, \sigma)$ }/ $\cong$ .

### 4. Twisted algebras of 3-dimensional Sklyanin algebras

In this section, we classify twisted algebras of 3-dimensional Sklyanin algebras. A 3dimensional Sklyanin algebra is a typical example of 3-dimensional quadratic AS-regular algebras. It is known that every 3-dimensional Sklyanin algebra is a geometric algebra  $\mathcal{A}(E,\sigma)$  where E is an elliptic curve in  $\mathbb{P}^2$  and  $\sigma$  is a translation by some point  $p \in E$ .

First, we recall some properties of elliptic curves in  $\mathbb{P}^2$ . Let *E* be an elliptic curve in  $\mathbb{P}^2$ . We use a *Hesse form* 

$$E = \mathcal{V}(x^3 + y^3 + z^3 - 3\lambda xyz)$$

where  $\lambda \in k$  with  $\lambda^3 \neq 1$ . It is known that every elliptic curve in  $\mathbb{P}^2$  can be written in this form (see [2, Corollary 2.18]). The *j*-invariant of a Hesse form E is given by

$$j(E) = \frac{27\lambda^3(\lambda^3 + 8)^3}{(\lambda^3 - 1)^3}$$

(see [2, Proposition 2.16]). The *j*-invariant j(E) classifies elliptic curves in  $\mathbb{P}^2$  up to projective equivalence (see [3, Theorem IV 4.1 (b)]). We fix the group structure on Ewith the zero element  $o := (1, -1, 0) \in E$  (see [2, Theorem 2.11]). For a point  $p \in E$ , a translation by p, denoted by  $\sigma_p$ , is an automorphism of E defined by  $\sigma_p(q) = p + q$ for every  $q \in E$ . We define  $\operatorname{Aut}_k(E, o) := \{\sigma \in \operatorname{Aut}_k E \mid \sigma(o) = o\}$ . It is known that  $\operatorname{Aut}_k(E, o)$  is a finite cyclic subgroup of  $\operatorname{Aut}_k E$  (see [3, Corollary IV 4.7]).

**Lemma 9** ([4, Theorem 4.6]). A generator of  $\operatorname{Aut}_k(E, o)$  is given by

(1)  $\tau_E(a, b, c) := (b, a, c)$  if  $j(E) \neq 0, 12^3$ ,

(2)  $\tau_E(a, b, c) := (b, a, \varepsilon c)$  if  $\lambda = 0$  (so that j(E) = 0),

(3)  $\tau_E(a,b,c) := (\varepsilon^2 a + \varepsilon b + c, \varepsilon a + \varepsilon^2 b + c, a + b + c)$  if  $\lambda = 1 + \sqrt{3}$  (so that  $j(E) = 12^3$ ) where  $\varepsilon$  is a primitive 3rd root of unity. In particular,  $\operatorname{Aut}_k(E, o)$  is a subgroup of  $\operatorname{Aut}_k(E \uparrow \mathbb{P}^2) = \operatorname{Aut}_k(\mathbb{P}^2 \downarrow E).$ 

Remark 10. When  $j(E) = 0, 12^3$ , we may fix  $\lambda = 0, 1 + \sqrt{3}$  respectively as in Lemma 9, because if two elliptic curves E and E' in  $\mathbb{P}^2$  are projectively equivalent, then for every  $\mathcal{A}(E,\sigma)$ , there exists an automorphism  $\sigma' \in \operatorname{Aut}_k E'$  such that  $\mathcal{A}(E,\sigma) \cong \mathcal{A}(E',\sigma')$  (see [7, Lemma 2.6]).

It follows from [4, Proposition 4.5] that every automorphism  $\sigma \in \operatorname{Aut}_k E$  can be written as  $\sigma = \sigma_p \tau_E^i$  where  $\sigma_p$  is a translation by a point  $p \in E$ ,  $\tau_E$  is a generator of  $\operatorname{Aut}_k(E, o)$ and  $i \in \mathbb{Z}_{|\tau_E|}$ . For any  $n \geq 1$ , we call a point  $p \in E$  n-torsion if np = o. We set  $E[n] := \{p \in E \mid np = o\}$  and  $T[n] := \{\sigma_p \in \operatorname{Aut}_k E \mid p \in E[n]\}$ . It follows from [4, Theorem 4.12 (3)] that every automorphism  $\sigma \in \operatorname{Aut}_k(\mathbb{P}^2 \downarrow E)$  can be written as  $\sigma = \sigma_q \tau_E^i$ where  $q \in E[3]$  and  $i \in \mathbb{Z}_{|\tau_E|}$ .

Let  $E = \mathcal{V}(x^3 + y^3 + z^3 - 3\lambda xyz)$  be an elliptic curve in  $\mathbb{P}^2$  and  $p = (a, b, c) \in E \setminus E[3]$ . Then  $\mathcal{A}(E, \sigma_p)$  is called a 3-dimensional Sklyanin algebra, and

$$\mathcal{A}(E,\sigma_p) = k\langle x, y, z \rangle / (ayz + bzy + cx^2, azx + bxz + cy^2, axy + byx + cz^2).$$

**Lemma 11** ([5, Lemma 4.10]). Let  $A = \mathcal{A}(E, \sigma_p)$  be a 3-dimensional Sklyanin algebra where  $p \in E \setminus E[3]$ .

- (1) For  $\sigma_q \tau_E^i \in \operatorname{Aut}_k(\mathbb{P}^2 \downarrow E)$ ,  $\sigma_q \tau_E^i \in Z(E, \sigma_p)$  if and only if  $p \tau_E^i(p) = o$ . (2) For  $\sigma_q \tau_E^i \in \operatorname{Aut}_k(\mathbb{P}^2 \downarrow E)$ ,  $\sigma_q \tau_E^i \in N(E, \sigma_p)$  if and only if  $p \tau_E^i(p) \in E[3]$ .
- (3)  $M(E, \sigma_p) = N(E, \sigma_p).$

By Theorem 8, to classify twisted algebras of 3-dimensional Sklyanin algebras  $\mathcal{A}(E, \sigma_p)$ up to isomorphism of graded algebras, it is enough to classify subsets  $Z(E, \sigma_p)$  and  $M(E, \sigma_p)$  of  $\operatorname{Aut}_k(\mathbb{P}^2 \downarrow E)$ .

**Theorem 12** ([5, Theorem 4.11]). Let  $A = \mathcal{A}(E, \sigma_p)$  be a 3-dimensional Sklyanin algebra. Then the following table gives  $Z(E, \sigma_p)$  and  $M(E, \sigma_p)$ ;

Type	j(E)	$Z(E,\sigma_p)$	$M(E,\sigma_p)$
	$j(E) \neq 0, 12^3$	$\begin{cases} T[3] & \text{if } p \notin E[2] \\ \operatorname{Aut}_k(\mathbb{P}^2 \downarrow E) & \text{if } p \in E[2] \end{cases}$	$\begin{cases} T[3] & \text{if } p \notin E[6] \\ \operatorname{Aut}_{k}(\mathbb{P}^{2} \downarrow E) & \text{if } p \in E[6] \end{cases}$
EC	j(E) = 0	$\begin{cases} T[3] & \text{if } p \notin E[2] \\ T[3] \rtimes \langle \tau_E^3 \rangle & \text{if } p \in E[2] \end{cases}$	$\begin{cases} T[3] & \text{if } p \notin \mathcal{E} \cup E[6] \\ \\ T[3] \rtimes \langle \tau_E^2 \rangle & \text{if } p \in \mathcal{E} \\ \\ T[3] \rtimes \langle \tau_E^3 \rangle & \text{if } p \in E[6] \end{cases}$
	$j(E) = 12^3$	$\begin{cases} T[3] & \text{if } p \notin E[2] \\ T[3] \rtimes \langle \tau_E^2 \rangle & \text{if } p \in E[2] \setminus \langle (1,1,\lambda) \rangle \\ \operatorname{Aut}_k(\mathbb{P}^2 \downarrow E) & \text{if } p = (1,1,\lambda) \end{cases}$	$\begin{cases} T[3] & \text{if } p \notin E[6] \\ T[3] \rtimes \langle \tau_E^2 \rangle & \text{if } p \in E[6] \setminus \mathcal{F} \\ \operatorname{Aut}_k(\mathbb{P}^2 \downarrow E) & \text{if } p \in \mathcal{F} \end{cases}$

where  $\mathcal{E} := \{(a, b, c) \in E \mid a^9 = b^9 = c^9\} \subset E[9] \setminus E[6] \text{ and } \mathcal{F} := \langle (1, 1, \lambda) \rangle \oplus E[3].$ 

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Katsushika division Institute of Arts and Sciences Tokyo University of Science 6-3-1 Niijuku, Katsushika-Ku, Tokyo, 125-8585, Japan

Email address: masaki.matsuno@rs.tus.ac.jp